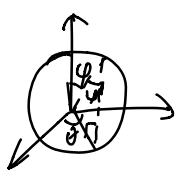


HW 13.

17.3

$$5. \iint_D \mathbf{F} \cdot d\mathbf{S} = \iiint_V \nabla \cdot \mathbf{F} \, dV$$



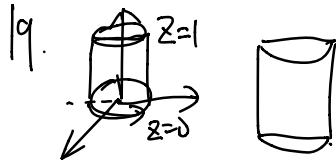
$$\begin{cases} x = r \sin \varphi \cos \theta & r: 0 \rightarrow 1 \\ y = r \sin \varphi \sin \theta & \theta: 0 \rightarrow 2\pi \\ z = r \cos \varphi & \varphi: 0 \rightarrow \pi \end{cases}$$

$$\nabla \cdot \mathbf{F} = z^2 \quad \text{also since } \left| \frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} \right| = r^2 \sin \varphi$$

$$\begin{aligned} \Rightarrow \iiint_V \nabla \cdot \mathbf{F} \, dV &= \int_0^1 \int_0^{2\pi} \int_0^\pi (r \cos \varphi)^2 (r^2 \sin \varphi) \, d\varphi \, d\theta \, dr \\ &= \int_0^1 r^4 \, dr \int_0^\pi \cos^2 \varphi \sin \varphi \, d\varphi \cdot 2\pi \\ &= \frac{1}{5} \cdot \frac{2}{3} \cdot 2\pi = \frac{4\pi}{15} \end{aligned}$$

$$\text{II. } \begin{cases} x = r \sin \varphi \cos \theta & r: 0 \rightarrow 2 \\ y = r \sin \varphi \sin \theta & \varphi: 0 \rightarrow \frac{\pi}{2} \\ z = r \cos \varphi & \theta: 0 \rightarrow \frac{\pi}{2} \end{cases} \quad \nabla \cdot \mathbf{F} = 3x^2 + 3z^2$$

$$\begin{aligned} \iiint_V \nabla \cdot \mathbf{F} \, dV &= \int_0^2 \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} 3r^2 (\sin^2 \varphi \cos^2 \theta + \cos^2 \varphi) r^2 \sin \varphi \, d\theta \, d\varphi \, dr \\ &= 3 \int_0^2 r^4 \, dr \left(\int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \sin^3 \varphi \cos^2 \theta \, d\theta \, d\varphi + \int_0^{\frac{\pi}{2}} \cos^2 \varphi \sin \varphi \, d\varphi \cdot \frac{\pi}{2} \right) \\ &= 3 \left(\frac{r^5}{5} \Big|_0^2 \right) \left(\int_0^{\frac{\pi}{2}} \sin^3 \varphi \, d\varphi \int_0^{\frac{\pi}{2}} \left(\frac{\cos 2\theta + 1}{2} \right) d\theta + \frac{\pi}{2} \cdot \frac{1}{3} \right) \\ &= \frac{3}{5} (2^5) \cdot \left(\frac{2}{3} \cdot \frac{1}{2} \cdot \frac{\pi}{2} + \frac{\pi}{6} \right) = \frac{32\pi}{5} \end{aligned}$$



$$4 = \iiint_W \nabla \cdot \mathbf{F} \, dV = \iint \mathbf{F} \cdot d\mathbf{s} \\ = \iint_{\partial W_{\text{side-curve}}} \mathbf{F} \cdot d\mathbf{s} + \iint_{\partial W_{\text{up}}} \mathbf{F} \cdot d\mathbf{s} + \iint_{\partial W_{\text{down}}} \mathbf{F} \cdot d\mathbf{s} + \iint_{\partial W_{\text{rectangle}}} \mathbf{F} \cdot d\mathbf{s}$$

$\iint_{\partial W_{\text{up}}} \mathbf{F} \cdot d\mathbf{s}$: parametrization of up bound:

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = 1 \end{cases}$$

$$\mathbf{r}(r, \theta) = (r \cos \theta, r \sin \theta, 1)$$

$$\vec{N} = \mathbf{r}_r \times \mathbf{r}_\theta = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos \theta & \sin \theta & 0 \\ -r \sin \theta & r \cos \theta & 0 \end{vmatrix} = (0, 0, r)$$

$$= \int_0^{2\pi} \int_0^1 (r^2 \sin^2 \theta, 0, 0) \cdot (0, 0, r) \, dr \, d\theta = 0$$

By same process we have $\iint_{\partial W_{\text{down}}} \mathbf{F} \cdot d\mathbf{s} = 0$

$\iint_{\partial W_{\text{rectangle}}} \mathbf{F} \cdot d\mathbf{s}$: parametrization:

$$\begin{cases} x = 0 \\ y = y \\ z = z \end{cases} \quad \mathbf{r}(y, z) = (0, y, z)$$

$$\mathbf{r}_y \times \mathbf{r}_z = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = (1, 0, 0)$$

~~the~~ normal vector should be outward.

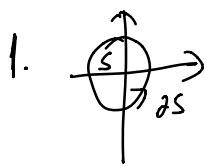
$$\text{So } \vec{N} = (-1, 0, 0) \text{ or } (-\mathbf{r}_y \times \mathbf{r}_z)$$

$$\Rightarrow \int_{-1}^1 \int_0^1 (zy^2, 0, 0) \cdot (-1, 0, 0) \, dz \, dy$$

$$= \int_{-1}^1 \int_0^1 -zy^2 \, dz \, dy = (-1) \left(\int_0^1 z \, dz \right) \left(\int_{-1}^1 y^2 \, dy \right) \\ = (-1) \left(\frac{1}{2} \right) \left(\frac{2}{3} \right)$$

$$\text{So } 4 = \iint_{\partial W_{\text{side-curve}}} \mathbf{F} \cdot d\mathbf{s} - \frac{1}{3} \Rightarrow \iint_{\partial W_{\text{side-curve}}} \mathbf{F} \cdot d\mathbf{s} = 4 + \frac{1}{3} = \frac{13}{3}$$

17.1

For the parametrization of ∂S :

$$\begin{cases} x = \cos\theta \\ y = \sin\theta \end{cases} \quad \theta: 0 \rightarrow 2\pi$$

$$\begin{aligned} & \int_0^{2\pi} (\cos\theta \sin\theta) (-\sin\theta) d\theta + \int_0^{2\pi} \sin\theta \cos\theta d\theta \\ &= \int_0^{2\pi} (-\sin^2\theta) \cos\theta d\theta + 0 \end{aligned}$$

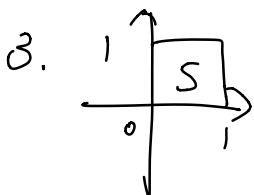
$$= 0$$

$$P = x, \quad Q = y$$

parametrization of S :

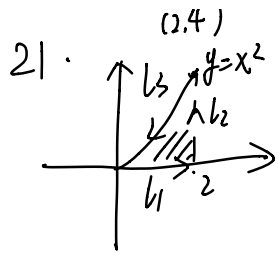
$$\begin{aligned} \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) ds &= \iint_S (0 - 1) ds & \begin{cases} x = r \cos\theta & r: 0 \rightarrow 1 \\ y = r \sin\theta & \theta: 0 \rightarrow 2\pi \end{cases} \\ &= \int_0^1 \int_0^{2\pi} (-1) r d\theta dr = 0 \end{aligned}$$

$$0 = 0 \quad \checkmark$$



By Green's theorem we have

$$\begin{aligned} & \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) ds \\ &= \iint_S (2x - 2y) ds \\ &= \int_0^1 \int_0^1 (2x - 2y) dx dy \\ &= \int_0^1 (x^2 - 2yx \Big|_0^1) dy \\ &= \int_0^1 (1 - 2y) dy = y - y^2 \Big|_0^1 = 0 \end{aligned}$$



$$Q = x \quad P = 0$$

$$S = \oint_{\partial D} (0)dx + (x)dy = \oint_{\partial D} x dy$$

$$= \int_{l_1} x dy + \int_{l_2} x dy + \int_{l_3} x dy$$

$$\downarrow$$

$$0$$

$$\int_0^4 (2) dy$$

8

$$\downarrow$$

$$r(x) = (x, x^2)$$

$$x: 2 \rightarrow 0$$

$$\int_2^0 x dx^2$$

$$= - \int_0^2 2x^2 dx$$

$$= -\frac{16}{3}$$

$$\Rightarrow S = 0 + 8 - \frac{16}{3} = \frac{8}{3}$$

$$29. \oint_{C_1} F \cdot d\vec{r} - \oint_{C_2} F \cdot d\vec{r} - \oint_{C_3} F \cdot d\vec{r}$$

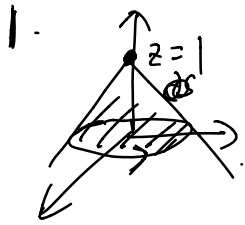
$$= \iint_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) ds = 9 \cdot (\pi 5^2 - 2\pi(1))$$

$$= 9(23\pi)$$

$$\Rightarrow \oint_{C_1} F \cdot d\vec{r} = \oint_{C_2} F \cdot d\vec{r} + \oint_{C_3} F \cdot d\vec{r} + 9(23\pi)$$

$$= 7\pi + 207\pi = 214\pi$$

17.2.



Stokes: $\oint_{\partial S} \vec{F} \cdot d\vec{r} = \iint_S (\text{curl } \vec{F}) \cdot d\vec{s}$

$\oint_{\partial S} \vec{F} \cdot d\vec{r}$

parametrization: $\begin{cases} x = \cos\theta \\ y = \sin\theta \end{cases}$

$\gamma(\theta) = (\cos\theta, \sin\theta, 0)$ $(0 - e^{z^2} \cdot 2z^2) i - (-\sin x \cdot 2z - e^{2z} \cdot 2z) j + (1 - (-1)) k$

$d\vec{r} = (-\sin\theta, \cos\theta, 0) d\theta$

$\oint_{\partial S} \vec{F} \cdot d\vec{r} = \int_0^{2\pi} \langle 2\cos\theta \sin\theta, \cos\theta, \sin\theta \rangle \cdot \langle -\sin\theta, \cos\theta, 0 \rangle d\theta$

$= \int_0^{2\pi} (-2\sin^2\theta \cos\theta + \cos^3\theta) d\theta$

$= \int_0^{2\pi} \cos^2\theta d\theta = \int_0^{2\pi} \left(\frac{\cos 2\theta + 1}{2}\right) d\theta = \pi$

$\text{curl } \vec{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}\right) i - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z}\right) j + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y}\right) k$

$= (1 - 2x)k \Rightarrow (0, 0, 1-2x)$

parametrization: $\begin{cases} x = r\cos\theta \\ y = r\sin\theta \\ z = 1-r^2 \end{cases} \quad \begin{matrix} r: 0 \rightarrow 1 \\ \theta: 0 \rightarrow 2\pi \end{matrix}$

$$\Rightarrow G(r, \theta) = (r \cos \theta, r \sin \theta, 1 - r^2)$$

$$G_r \times G_\theta = \begin{vmatrix} \hat{i} & \hat{j} & k \\ \cos \theta & \sin \theta & -2r \\ -r \sin \theta & r \cos \theta & 0 \end{vmatrix} = 2r^2 \cos \theta \hat{i} - (-2r^2 \sin \theta) \hat{j} + r \hat{k}$$

$$\Rightarrow (2r^2 \cos \theta, 2r^2 \sin \theta, r)$$

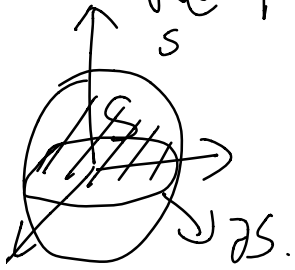
$$\int_0^{2\pi} \int_0^1 (0, 0, 1 - 2r \cos \theta) \cdot (2r^2 \cos \theta, 2r^2 \sin \theta, r) \, dr \, d\theta$$

$$= \int_0^{2\pi} \int_0^1 (r - 2r^2 \cos \theta) \, dr \, d\theta$$

$$= \frac{1}{2} \times 2\pi = \pi$$

$$\pi = \pi \quad \checkmark$$

$$5. \int_S (\text{curl } \vec{F}) \cdot d\vec{s} = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$



The parametrization of the ∂S

$$\partial S: \begin{cases} x = \cos\theta \\ y = \sin\theta \\ z = 0 \end{cases} \quad \theta = 0 \rightarrow 2\pi.$$

$$\vec{r}(\theta) = (\cos\theta, \sin\theta, 0)$$

$$d\vec{r} = (-\sin\theta, \cos\theta, 0) d\theta$$

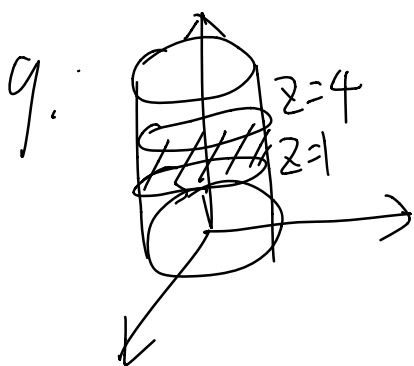
$$\vec{F} = \langle 1 - \sin\theta, 1 + \cos\theta, 1 \rangle$$

$$\int_0^{2\pi} \langle 1 - \sin\theta, 1 + \cos\theta, 1 \rangle \cdot \langle -\sin\theta, \cos\theta, 0 \rangle d\theta$$

$$= \int_0^{2\pi} (-\sin\theta + \sin\theta^2 + \cos\theta + \cos\theta^2) d\theta$$

$$= 2\pi.$$

$$\text{curl } \vec{F} = \langle -3z^2 e^{z^3}, 2z e^{z^2} + z \sin(xz), 2 \rangle$$



$$\iint_S (\text{Curl } \vec{F}) \cdot d\vec{S}$$

$$= \oint_{\partial S} \vec{F} \cdot d\vec{r}$$

$$= \oint_{l_1} \vec{F} \cdot d\vec{r} + \oint_{l_2} \vec{F} \cdot d\vec{r}$$



$$l_1: \begin{cases} x = \cos \theta & \theta: 0 \rightarrow 2\pi \\ y = \sin \theta & \gamma(\theta) = (\cos \theta, \sin \theta, 1) \\ z = 1 & d\vec{r} = (-\sin \theta, \cos \theta, 0) d\theta \end{cases}$$

$$\vec{F} = \langle \sin \theta, \cos \theta, \cos \theta \sin \theta \rangle$$

$$\int_0^{2\pi} \langle \sin \theta, \cos \theta, \cos \theta \sin \theta \rangle$$

$$\cdot \langle -\sin \theta, \cos \theta, 0 \rangle d\theta$$

$$= \int_0^{2\pi} \cos 2\theta d\theta = 0$$

$$l_2: \begin{cases} x = \cos\theta \\ y = \sin\theta \\ z = 4 \end{cases} \quad \vec{F} = \langle 4\sin\theta, -4\cos\theta, 4^3 \rangle$$

$$= \langle 4\sin\theta, -4\cos\theta, 64 \rangle$$

$$r(\theta) = \langle \cos\theta, \sin\theta, 4 \rangle$$

$$\int_0^{2\pi} \langle 4\sin\theta, -4\cos\theta, 64 \rangle$$

$$\cdot \langle -\sin\theta, \cos\theta, 0 \rangle d\theta$$

$$= 0$$

$$S_0: \iint_S (\text{curl } \vec{F}) \cdot d\vec{S} = 0,$$